PATENT COOPERATION TREATY

PCT

REC'D 3 0 AUG 2005

INTERNATIONAL PRELIMINARY REPORT ON PATENTABILITY

(Chapter II of the Patent Cooperation Treaty)

(PCT Article 36 and Rule 70)

Applicant's or agent's file reference 88TY1319	FOR FURTHER AC	CTION	See Form PCT/IPEA/416		
international application No. PCT/IB2004/002931	International filing date (09.09.2004	day/month/year)	Priority date <i>(day/monthlyear)</i> 11.09.2003		
International Patent Classification (IPC) or national classification and IPC G01S17/93, G01S13/93, G01S17/89, G01S13/86, G01S17/87					
Applicant TOYOTA JIDOSHA KABUSHIKI KAISHA et al.					
 This report is the international preliminary examination report, established by this International Preliminary Examining Authority under Article 35 and transmitted to the applicant according to Article 36. 					
This REPORT consists of a total of 4 sheets, including this cover sheet.					
3. This report is also accompanied by	This report is also accompanied by ANNEXES, comprising:				
a. 🛭 sent to the applicant and to	a. 🗵 sent to the applicant and to the International Bureau) a total of 3 sheets, as follows:				
sheets of the description, claims and/or drawings which have been amended and are the basis of this report and/or sheets containing rectifications authorized by this Authority (see Rule 70.16 and Section 607 of the Administrative Instructions).					
sheets which supersede earlier sheets, but which this Authority considers contain an amendment that goes beyond the disclosure in the international application as filed, as indicated in item 4 of Box No. I and the Supplemental Box.					
b. (sent to the International Bureau only) a total of (indicate type and number of electronic carrier(s)), containing a sequence listing and/or tables related thereto, in computer readable form only, as indicated in the Supplemental Box Relating to Sequence Listing (see Section 802 of the Administrative Instructions).					
. WE down to .					
4. This report contains indications relating to the following items:					
Box No. I Basis of the opin	nion				
☐ Box No. II Priority					
_	-	rd to novelty, inventive s	step and industrial applicability		
Box No. IV Lack of unity of					
☐ Box No. V Reasoned state applicability; cita	ment under Article 35(2 ations and explanations	 with regard to novelty, supporting such statem 	inventive step or industrial ent		
☐ Box No. VI Certain docume					
l .	in the international app		e et l isa.		
☐ Box No. VIII Certain observa	ations on the internation	al application			
Date of submission of the demand		Date of completion of this	s report		
24.05.2005		26.08.2005			
Name and mailing address of the international		Authorized Officer	neines Pateorean.		
preliminary examining authority: European Patent Office D-80298 Munich Tel. +49 89 2399 - 0 Tx: 523656 epmu d Fax: +49 89 2399 - 4465		Johansson, R Telephone No. +49 89 23	The state of the s		

INTERNATIONAL PRELIMINARY REPORT ON PATENTABILITY

International application No. PCT/IB2004/002931

_	Box No. I Basis of the report			
1.	. With regard to the language , this report is based on the international application in the language in which it filed, unless otherwise indicated under this item.			
	This report is based on translations from the original language into the following language, which is the language of a translation furnished for the purposes of:			
		der Rules 12.3 and 23.1(b)) itional application (under Rule 12.4) examination (under Rules 55.2 and/or 55.3)		
2.	Vith regard to the elements* of the international application, this report is based on <i>(replacement sheets which</i> have been furnished to the receiving Office in response to an invitation under Article 14 are referred to in this eport as "originally filed" and are not annexed to this report):			
	Description, Pages			
	1-14	as originally filed		
	Claims, Numbers			
	7-12	as originally filed		
	1-6	received on 24.05.2005 with letter of 24.05.2005		
	Drawings, Sheets			
	1/3-3/3	as originally filed		
	☐ a sequence listing and/or ar	ny related table(s) - see Supplemental Box Relating to Sequence Listing		
3. [The amendments have resulted in the cancellation of:			
	☐ the description, pages ☐ the claims, Nos.			
	☐ the drawings, sheets/figs			
	☐ the sequence listing (spe☐ any table(s) related to se			
4.	This report has been established as if (some of) the amendments annexed to this report and listed below had not been made, since they have been considered to go beyond the disclosure as filed, as indicated in the Supplemental Box (Rule 70.2(c)).			
	☐ the description, pages			
	☐ the claims, Nos.☐ the drawings, sheets/figs	· · · · · · · · · · · · · · · · · · ·		
	☐ the sequence listing (spe	ecify):		
	☐ any table(s) related to se			
	* If item 4 annlies so	ome or all of these sheets may be marked "superseded "		

INTERNATIONAL PRELIMINARY REPORT ON PATENTABILITY

International application No. PCT/IB2004/002931

Box No. V Reasoned statement under Article 35(2) with regard to novelty, inventive step or industrial applicability; citations and explanations supporting such statement

1. Statement

Novelty (N) Yes: Claims 1-6

No: Claims

Inventive step (IS) Yes: Claims 1-6

No: Claims

Industrial applicability (IA) Yes: Claims 1-6

No: Claims

2. Citations and explanations (Rule 70.7):

see separate sheet

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Re Item V

Reasoned statement under Rule 66.2(a)(ii) with regard to novelty, inventive step or industrial applicability; citations and explanations supporting such statement

Reference is made to D1=WO 02/103385.

D1 discloses (cf p. 32, l. 13-p. 34, l. 14 and p. 37, l. 1 - p. 38, l. 15) an object detection system in which objects are fused by either comparing the radar image with camera image or vice versa. However, D1 does not suggest to do both comparisons and then compare the resulting objects of the two independent comparisons to determine if they coincide and if so determining that the objects are the same. Moreover, there is no hint in the prior art to modify D1 towards the invention in order to increase the accuracy of detection.

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Claims

1. An object detection system including radar detection means (2) that detects an object using a radar, image detection means (3) that detects an object using an image, and collating means (4) that performs collation between a detection result of the radar detection means (2) and a detection result of the image detection means (3),

the object detection system being characterized in that the collating means (4) detects a combination of an object detected by the radar detection means (2) and an object selected among those detected by the image detection means (3), which is the closest to the object detected by the radar detection means (2), detects a combination of an object detected by the image detection means (3) and an object selected among those detected by the radar detection means (2), which is the closest to the object detected by the image detection means (3), determines whether there is a coincidence between the combination of the object detected by the radar detection means (2) and the selected object as being closest thereto and the combination of the object detected by the image detection means (3) and the selected object as being closest thereto, and determines, when there is the coincidence, that the object detected by the radar detection means (2) is the same as the object detected by the image detection means (3).

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2. The object detection system according to claim 1, characterized in that the radar detection means (2) comprises at least one of a millimeter-wave radar and a laser radar.

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- 3. The object detection system according to claim 1 or 2, characterized in that the image detection means (3) comprises a stereo camera.
- 4. A method of detecting an object in a system (1) including radar detection means (2) that detects an object using a radar, image detection means (3) that detects an object using an image, and collating means (4) that performs collation between a detection result of the radar detection means (2) and a detection result of the image detection means (3),

the method being characterized by comprising the steps of

detecting a combination of an object detected by the radar detection means (2) and an object selected among those detected by the image detection means (3), which is the closest to the object detected by the radar detection means (S1, S2);

detecting a combination of an object detected by the image detection means (3) and an object selected among those detected by the radar detection means (2), which is the closest to the object detected by the image detection means (S3, S4);

determining whether there is a coincidence between
the combination of the object detected by the radar
detection means (2) and the selected object as being
closest thereto and the combination of the object
detected by the image detection means (3) and the
selected object as being closest thereto; and

determining, when there is the coincidence, that the object detected by the radar detection means (2) is the same as the object detected by the image detection means (S5).

- 5. The method according to claim 4, characterized in that the radar detection means (2) comprises at least one of a millimeter-wave radar and a laser radar.
- 5 6. The method according to claim 4 or 5, characterized in that the image detection means (3) comprises a stereo camera.

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